

## 2-L Channel Routing: Basic Left-Edge Algorithm

- Hashimoto & Stevens, “Wire routing by optimizing channel assignment within large apertures,” DAC-71.
- **No vertical constraint.**
- HV-layer model is used.
- **Doglegs are not allowed.**
- Treat each net as an interval.
- Intervals are sorted according to their left-end  $x$ -coordinates.
- Intervals (nets) are routed one-by-one according to the order.
- For a net, tracks are scanned from top to bottom, and the first track that can accommodate the net is assigned to the net.
- Optimality: produces a routing solution with the minimum # of tracks (if no vertical constraint).

## Basic Left-Edge Algorithm

**Algorithm: Basic\_Left-Edge**( $U, track[j]$ )

$U$ : set of unassigned intervals (nets)  $I_1, \dots, I_n$ ;

$I_j = [s_j, e_j]$ : interval  $j$  with left-end  $x$ -coordinate  $s_j$  and right-end  $e_j$ ;

$track[j]$ : track to which net  $j$  is assigned.

1 **begin**

2  $U \leftarrow \{I_1, I_2, \dots, I_n\}$ ;

3  $t \leftarrow 0$ ;

4 **while** ( $U \neq \emptyset$ ) **do**

5  $t \leftarrow t + 1$ ;

6  $watermark \leftarrow 0$ ;

7 **while** (there is an  $I_j \in U$  s.t.  $s_j > watermark$ ) **do**

8     Pick the interval  $I_j \in U$  with  $s_j > watermark$ ,  
   nearest  $watermark$ ;

9      $track[j] \leftarrow t$ ;

10     $watermark \leftarrow e_j$ ;

11     $U \leftarrow U - \{I_j\}$ ;

12 **end**



# Constrained Left-Edge Algorithm

**Algorithm: Constrained\_Left-Edge( $U, track[j]$ )**

$U$ : set of unassigned intervals (nets)  $I_1, \dots, I_n$ ;

$I_j = [s_j, e_j]$ : interval  $j$  with left-end  $x$ -coordinate  $s_j$  and right-end  $e_j$ ;

$track[j]$ : track to which net  $j$  is assigned.

1 **begin**

2  $U \leftarrow \{I_1, I_2, \dots, I_n\}$ ;

3  $t \leftarrow 0$ ;

4 **while** ( $U \neq \emptyset$ ) **do**

5  $t \leftarrow t + 1$ ;

6  $watermark \leftarrow 0$ ;

7 **while** (there is an **unconstrained**  $I_j \in U$  s.t.  $s_j > watermark$ ) **do**

8     Pick the interval  $I_j \in U$  that is unconstrained,  
   with  $s_j > watermark$ , nearest  $watermark$ ;

9      $track[j] \leftarrow t$ ;

10     $watermark \leftarrow e_j$ ;

11     $U \leftarrow U - \{I_j\}$ ;

12 **end**

## Constrained Left-Edge Example

- $I_1 = [1, 3]$ ,  $I_2 = [1, 5]$ ,  $I_3 = [6, 8]$ ,  $I_4 = [10, 11]$ ,  $I_5 = [2, 6]$ ,  $I_6 = [7, 9]$ .
- Track 1: Route  $I_1$  (cannot route  $I_3$ ); Route  $I_6$ ; Route  $I_4$ .
- Track 2: Route  $I_2$ ; cannot route  $I_3$ .
- Track 3: Route  $I_5$ .
- Track 4: Route  $I_3$ .

